



SPARE PART SIMOTION DRIVE-BASED CONTROLLER EXTENSION CX32; INVERTER CONTROL MODULE; TO INCREASE DRIVE COUNT ON SIMOTION D4X5; INTERFACES: 4 DI, 4 DI/DO, 4 DRIVE-CLiQ

| | |
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| product brand name | SIMOTION |
| product type designation | CX32 |
| Version of the motion control system | Controller Extension |
| Integrated drive control / header | |
| Maximum number of axes for integrated drive control | |
| • servo | 6 |
| • vector | 4 |
| • V/f | 8 |
| • note | Alternative control modes; drive control based on SINAMICS S120 CU320, firmware version V2.x |
| Communication | |
| Interfaces | |
| • DRIVE-CLiQ | 4 |
| General technical data | |
| Fan | No fan |
| DC supply voltage | |
| • rated value | 24 V |
| • minimum | 20.4 V |
| • maximum | 28.8 V |
| consumed current / typical | 800 mA |
| • note | with no load on inputs/outputs, no 24 V supply via DRIVE-CLiQ interface |
| Making current, typ. | 1.6 A |
| Power loss, typ. | 20 W |
| Ambient temperature, during | |
| • storage | -40 ... +70 °C |
| • transport | -40 ... +70 °C |
| • operation | 0 ... 55 °C |
| — note | Maximum 5000 m (16405 ft) above sea level. Above an altitude of 2000 m (6562 ft), the max. ambient temperature decreases by 7 °C (12.6 °F) every 1000 m (3281 ft). |
| Relative humidity | |
| • during operation | 5 ... 95 % |
| • without condensation, tested acc. to IEC 60068-2-38 | Wert fehlt |
| Air pressure | 700 ... 1 060 hPa |
| Degree of protection | IP20 / UL open type |
| height | 380 mm |
| width | 25 mm |
| • depth | 270 mm |
| • Depth / Note | When the spacer is removed 230 mm (9.05 in) deep |

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| net weight | 2 200 g |
| Digital inputs / header | |
| number of digital inputs | 4 |
| DC input voltage | |
| • rated value | 24 V |
| • for signal "1" | 15 ... 30 V |
| • for signal "0" | -3 ... +5 V |
| Electrical isolation | Yes |
| • note | Yes, in groups of 4 |
| Current consumption for "1" signal level, typ. | 10 mA |
| Input delay time for | |
| • signal "0" → "1", typ. | 50 µs |
| • signal "1" → "0", typ. | 150 µs |
| Digital inputs/outputs / header | |
| Number of digital I/Os | 4 |
| Parameterization possibility of the digital I/Os | parameterizable as DI, as DO, as probe input (max. 3) |
| If used as an input / header | |
| DC input voltage | |
| • rated value | 24 V |
| • for signal "1" | 15 ... 30 V |
| • for signal "0" | -3 ... +5 V |
| Electrical isolation | No |
| Current consumption for "1" signal level, typ. | 10 mA |
| Input delay time for DI 9 to DI 11 for | |
| • signal "0" → "1", typ. | 5 µs |
| • signal "1" → "0", typ. | 50 µs |
| — note | can also be used as probe inputs |
| Input delay time for DI 8 for | |
| • signal "0" → "1", typ. | 50 µs |
| • signal "1" → "0", typ. | 100 µs |
| Measuring input / reproducibility | 5 µs |
| If used as an output / header | |
| Load voltage | |
| • rated value | 24 V |
| • minimum | 20.4 V |
| • maximum | 28.8 V |
| Electrical isolation | No |
| Current carrying capacity for each output, max. | 500 mA |
| Leakage current, max. | 2 mA |
| Output delay for | |
| • signal "0" → "1", typ. | 150 µs |
| • signal "0" → "1", max. | 400 µs |
| • signal "1" → "0", typ. | 75 µs |
| • signal "1" → "0", max. | 100 µs |
| — note | Data for Vcc = 24 V; load 48 Ohm; "1" = 90 % VOut, "0" = 10 % VOut |
| Switching frequency of the outputs for | |
| • resistive load, max. | 100 Hz |
| • inductive load, max. | 2 Hz |
| • lamp load, max. | 11 Hz |
| Short-circuit protection | Yes |
| Additional technical data | |
| Back-up of non-volatile data | |
| • of retentive data | unlimited buffer duration |
| Approvals | |
| • USA | cULus |
| • Canada | cULus |
| • Australia | RCM (formerly C-Tick) |



