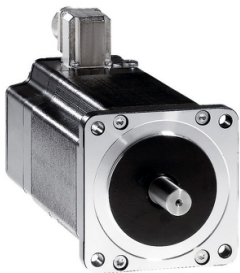


Product data sheet

Specifications



3-phase stepper motor - 6.78 Nm - shaft $\varnothing$ 14mm - L=128mm - w/o brake - conn

BRS39BW460ACB

 **Discontinued on:** Oct 9, 2023

 **Discontinued**

Main

Range compatibility	Lexium SD3
Product or component type	Motion control motor
Device short name	BRS3
Maximum mechanical speed	3000 rpm
Motor type	3-phase stepper motor
Number of motor poles	6
Supply voltage limits	230 V AC 325 V DC
Mounting support	Flange
Motor flange size	3.3 in (85 mm)
Length	6.7 in (171 mm)
Centring collar diameter	2.4 in (60 mm)

Complementary

Centring collar depth	0.08 in (2 mm)
Number of mounting holes	4
Mounting holes diameter	0.3 in (6.5 mm)
Circle diameter of the mounting holes	3.90 in (98.99 mm)
Electrical connection	Connector
Holding brake	Without
Shaft end	Untapped
Second shaft	With second shaft end
Shaft diameter	0.6 in (14 mm)
Shaft length	1.2 in (30 mm)
Nominal torque	53.1 lbf.in (6 N.m)
Peak stall torque	51.16 lbf.in (5.78 N.m)
Continuous stall torque	51.16 lbf.in (5.78 N.m)
Holding torque	60.008 lbf.in (6.78 N.m)
Rotor inertia	3.3 kg.cm ²
Resolution	1.8 °, 0.9 °, 0.72 °, 0.36 °, 0.18 °, 0.09 °, 0.072 °, 0.036 ° step angle 200, 400, 500, 1000, 2000, 4000, 5000, 10000 steps number of full steps per revolution

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

Accuracy error	+/- 6 arc min
Maximum starting frequency	5.3 kHz
[In] rated current	2.25 A
Resistance	6.5 Ohm winding)
Time constant	10 ms
Maximum radial force Fr	110 N first shaft end) 50 N second shaft end)
Maximum axial force Fa	175 N tensile force) 30 N force pressure)
Service life in hours	20000 h bearing)
Angular acceleration	200000 rad/s²
Net weight	9.5 lb(US) (4.3 kg)

Environment

Standards	IEC 50347 IEC 60072-1
Type of cooling	Natural convection
Ambient air temperature for operation	-13...104 °F (-25...40 °C)
Ambient air temperature for storage	-13...158 °F (-25...70 °C)
Operating altitude	<= 1000 m without power derating
Relative humidity	15...85 % without condensation
Vibration resistance	20 m/s² maximum A IEC 60034-14
IP degree of protection	IP41 shaft bushing: conforming to IEC 60034-5 IP56 total except shaft bushing: conforming to IEC 60034-5
Temperature class	F winding IEC 60034-1

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	4.3 in (11.0 cm)
Package 1 Width	7.5 in (19.0 cm)
Package 1 Length	15.6 in (39.5 cm)
Package 1 Weight	9.9 lb(US) (4.5 kg)

Contractual warranty

Warranty (in months)	18
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Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing “Use Better, Use Longer, Use Again” campaign to extend product lifetimes and recyclability.

[Environmental Data explained >](#)

[How we assess product sustainability >](#)

Use Better

Materials and Substances	
EU RoHS Directive	Compliant By Exemption
PVC free	Yes

Use Longer

Lifetime extension	
Repair	No

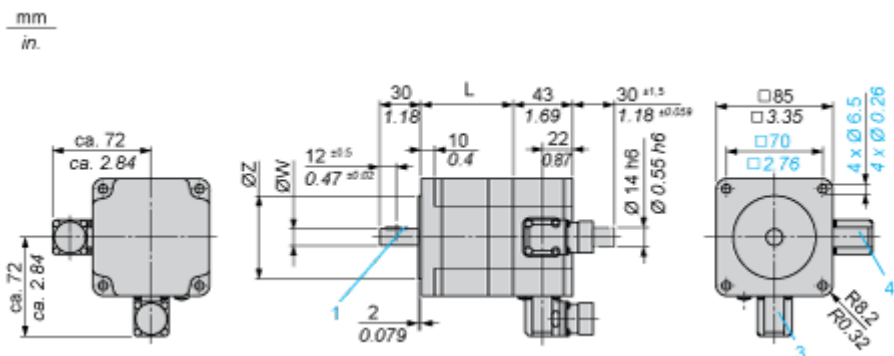
Use Again

Repack and remanufacture	
Circularity Profile	No need of specific recycling operations
WEEE Label	 The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

Dimensions Drawings

Dimensions

3-Phase Stepper Motor in Connector Version



- 3 : Motor connection 6 poles
- 4 : Motor connection (optional) 12 poles

Dimensions in mm

L	Shaft diameter ØW	Centring collar ØZ	Woodruff key DIN 6888 (1)
127.5 (+0.6) (-0.8)	14 h6	60 h8	5 x 6.5

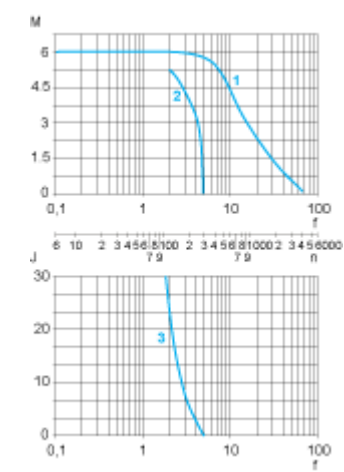
Dimensions in in.

L	Shaft diameter ØW	Centring collar ØZ	Woodruff key DIN 6888 (1)
5.02 (+0.023) (-0.031)	0.55 h6	2.36 h8	0.20 x 0.25

Performance Curves

Torque Characteristics

Measurement at 1000 Steps/Revolution, Nominal Voltage DC Bus U_N and Phase Current I_N



- M : Torque in Nm
- n : Speed in rpm
- f : Frequency in kHz
- J : Rotor inertia in $\text{kg}\cdot\text{cm}^2$
- 1 : Pull-out torque
- 2 : Pull-in torque
- 3 : Maximum load inertia