

Product data sheet

Specifications



servo motor BMI 3-phase - untapped IP65 single turn - 131072 p/t - brake

BMI0703P21F

⚠ Discontinued on: Jun 30, 2023

⚠ Discontinued

Main

Range compatibility	Lexium 32i
Device short name	BMI
Product or component type	Servo motor with power stage

Complementary

Maximum mechanical speed	8000 rpm
[Us] rated supply voltage	208...480 V - 15...10 %
Supply voltage limits	208...480 V
Network number of phases	Three phase
Supply frequency	50/60 Hz - 5...5 %
Network frequency limits	47.5...63 Hz
EMC filter	Integrated
Continuous output current	2 A 8 kHz
Output current 3s peak	6 A 400 V 3 s
Continuous stall current	2 A
Continuous stall torque	30.09 lbf.in (3.4 N.m) 208...480 V three phase
Peak stall torque	76.1 lbf.in (8.6 N.m) 208 V three phase 76.1 lbf.in (8.6 N.m) 400 V three phase 76.1 lbf.in (8.6 N.m) 480 V three phase
Nominal output power	900 W 400 V three phase 900 W 480 V three phase 450 W 208 V three phase
Nominal torque	25.7 lbf.in (2.9 N.m) 208 V three phase 23.9 lbf.in (2.7 N.m) 400 V three phase 20.4 lbf.in (2.3 N.m) 480 V three phase
Nominal speed	3300 rpm 400 V three phase 1600 rpm 208 V three phase 3900 rpm 480 V three phase
Maximum current Irms	12.5 A 400 V, three phase 12.5 A 480 V, three phase 12.5 A 208 V, three phase
Product compatibility	Drive control unit LXM32i CANopen Drive control unit LXM32i EtherCAT
Shaft end	Untapped
Second shaft	Without second shaft end
Shaft diameter	0.6 in (14 mm)

Disclaimer: This documentation is not intended as a substitute for and is not to be used for determining suitability or reliability of these products for specific user applications

Shaft length	1.2 in (30 mm)
Feedback type	Absolute single turn SinCos Hiperface
Speed feedback resolution	131072 points/turn
Holding brake	With
Holding torque	26.6 lbf.in (3 N.m) holding brake
Mounting support	International standard flange
Motor flange size	2.8 in (70 mm)
Electrical connection	Printed circuit board connector
Torque constant	1.41 N.m/A 68 °F (20 °C)
Back emf constant	95.39 V/krpm 68 °F (20 °C)
Number of motor poles	10
Rotor inertia	1.78 kg.cm²
Stator resistance	7.99 Ohm 68 °F (20 °C)
Stator inductance	25.6 mH 68 °F (20 °C)
Stator electrical time constant	3.2 ms 68 °F (20 °C)
Maximum radial force Fr	730 N 1000 rpm 580 N 2000 rpm 510 N 3000 rpm 460 N 4000 rpm 430 N 5000 rpm 400 N 6000 rpm
Maximum axial force Fa	0.2 x Fr
Brake pull-in power	5 W
Type of cooling	Natural convection
Length	13.3 in (339 mm)
Number of motor stacks	3
Centring collar diameter	2.4 in (60 mm)
Centring collar depth	0.10 in (2.5 mm)
Number of mounting holes	4
Mounting holes diameter	0.2 in (5.5 mm)
Circle diameter of the mounting holes	3.0...3.2 in (75...82 mm)
Distance shaft shoulder-flange	0.10 in (2.5 mm)

Environment

IP degree of protection	IP65
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Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	9.8 in (25.0 cm)
Package 1 Width	7.3 in (18.6 cm)
Package 1 Length	21.7 in (55.0 cm)
Package 1 Weight	14.3 lb(US) (6.5 kg)

Contractual warranty

Warranty (in months)	18
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Environmental Data

Schneider Electric aims to achieve Net Zero status by 2050 through supply chain partnerships, lower impact materials, and circularity via our ongoing “Use Better, Use Longer, Use Again” campaign to extend product lifetimes and recyclability.

[Environmental Data explained >](#)

[How we assess product sustainability >](#)



Environmental footprint

Environmental Disclosure

[Product Environmental Profile](#)

Use Better



Materials and Substances

Packaging made with recycled cardboard

Yes

Packaging without single use plastic

No

EU RoHS Directive

[Compliant By Exemption](#)

REACH Regulation

[Reference contains Substances of Very High Concern above the threshold](#)

PVC free

Yes

Use Longer



Lifetime extension

Repair

No

Use Again



Repack and remanufacture

Circularity Profile

[End of Life Information](#)

Take-back

Nej

WEEE Label

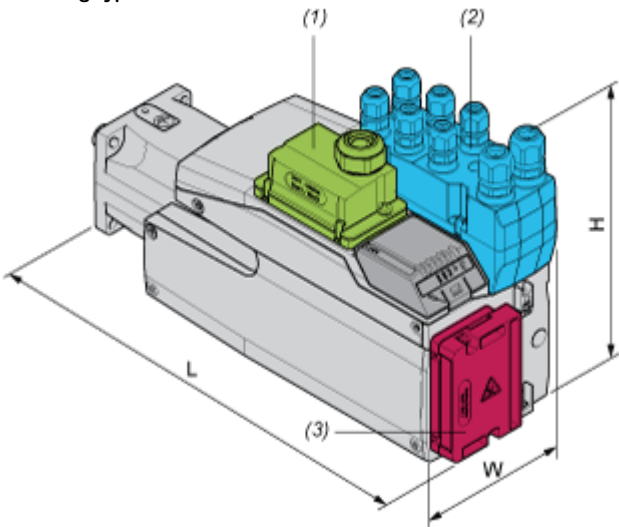


The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins

Dimensions Drawings

External Dimensions

With Standard Braking Resistor
Mounting type A



- (1) Module for supply voltage
- (2) I/O module
- (3) Standard braking resistor

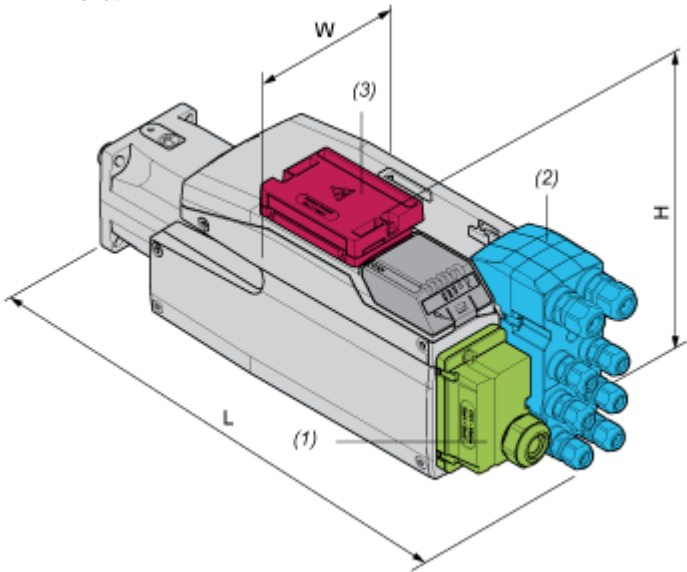
Dimensions in mm

W	H	L
99	187	360

Dimensions in in.

W	H	L
3,90	7,36	14,17

Mounting type B



- (1) Module for supply voltage
- (2) I/O module

(3) Standard braking resistor

Dimensions in mm

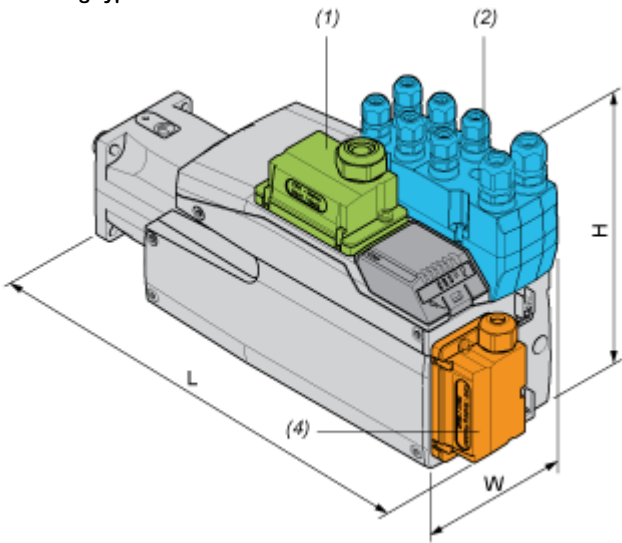
W	H	L
99	138,5	409

Dimensions in in.

W	H	L
3,90	5,45	16,1

With External Braking Resistor

Mounting type C



- (1) Module for supply voltage
- (2) I/O module
- (4) External braking resistor

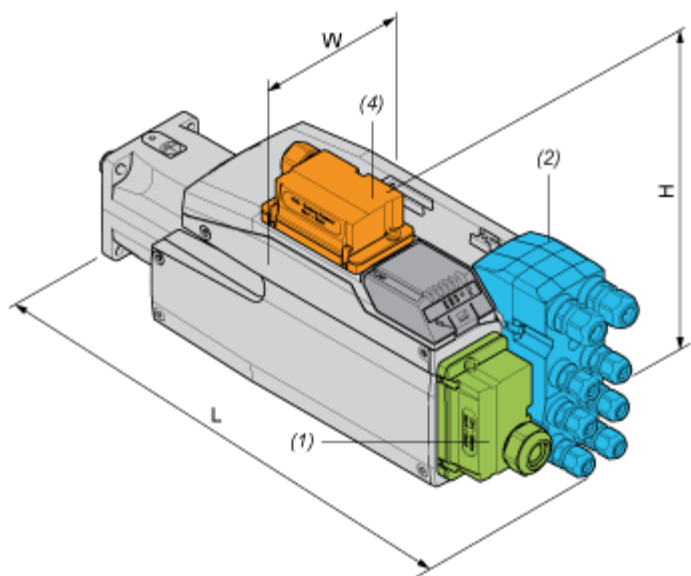
Dimensions in mm

W	H	L
99	187	372

Dimensions in in.

W	H	L
3,90	7,36	14,65

Mounting type D



- (1) Module for supply voltage
- (2) I/O module
- (4) External braking resistor

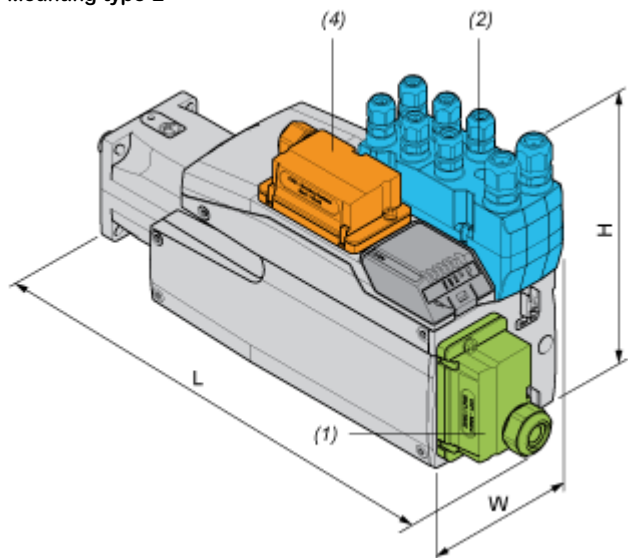
Dimensions in mm

W	H	L
99	160	409

Dimensions in in.

W	H	L
3,90	6,3	16,1

Mounting type E



- (1) Module for supply voltage
- (2) I/O module
- (4) External braking resistor

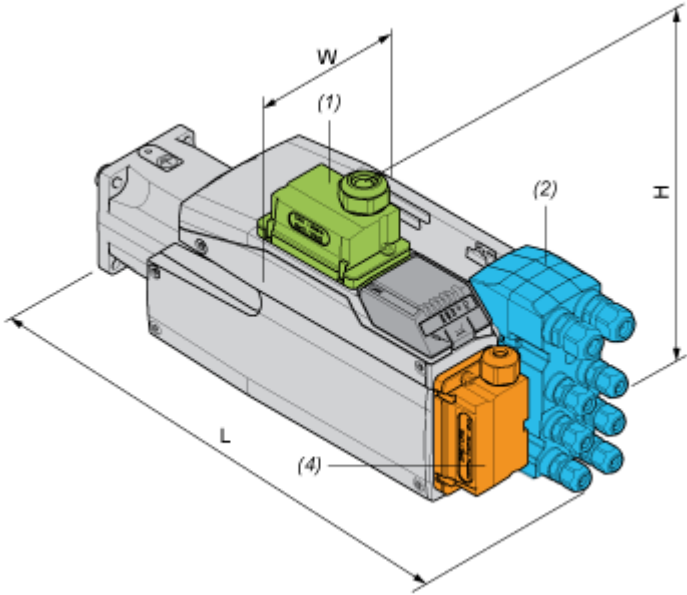
Dimensions in mm

W	H	L
99	187	399

Dimensions in in.

W	H	L
3,90	7,36	15,71

Mounting type F



- (1) Module for supply voltage
- (2) I/O module
- (4) External braking resistor

Dimensions in mm

W	H	L
99	180	409

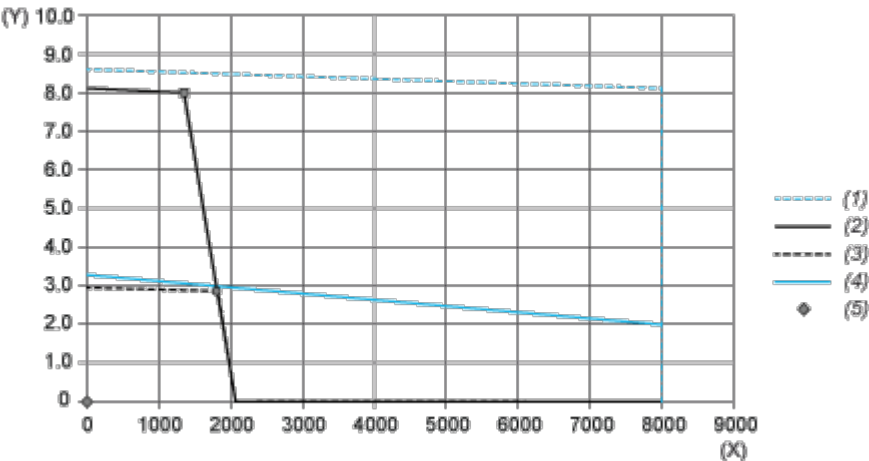
Dimensions in in.

W	H	L
3,90	7,09	16,1

Performance Curves

Performance Curves

Torque/Speed Curves with 208 V Three Phases Supply Voltage

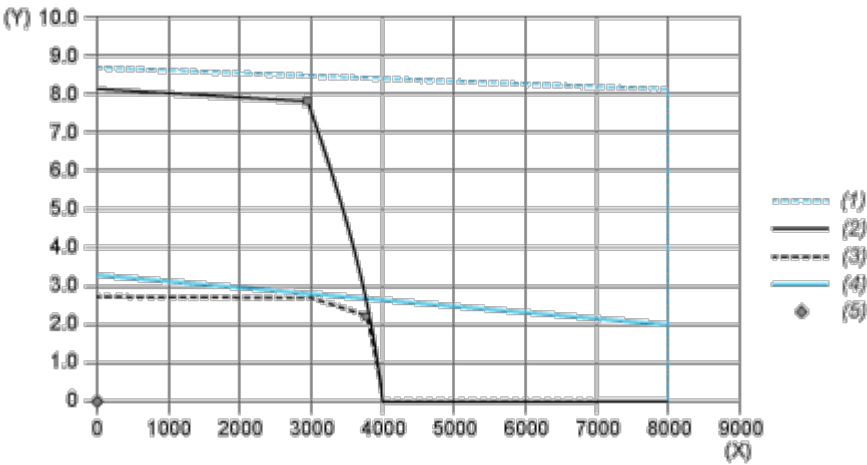


- (X) Speed (rpm)
- (Y) Torque (N.m)
- (1) Motor peak
- (2) Drive peak
- (3) Drive cont
- (4) Motor cont
- (5) Operating point

		Power	At Speed	With Torque
max. Peak Power	■	1138 W	1360 rpm	7.99 N.m
max Cont. Power (Drive)	●	564 W	1840 rpm	2.93 N.m

Performance Curves

Torque/Speed Curves with 400 V Three Phases Supply Voltage



(X) Speed (rpm)

(Y) Torque (N.m)

(1) Motor peak

(2) Drive peak

(3) Drive cont

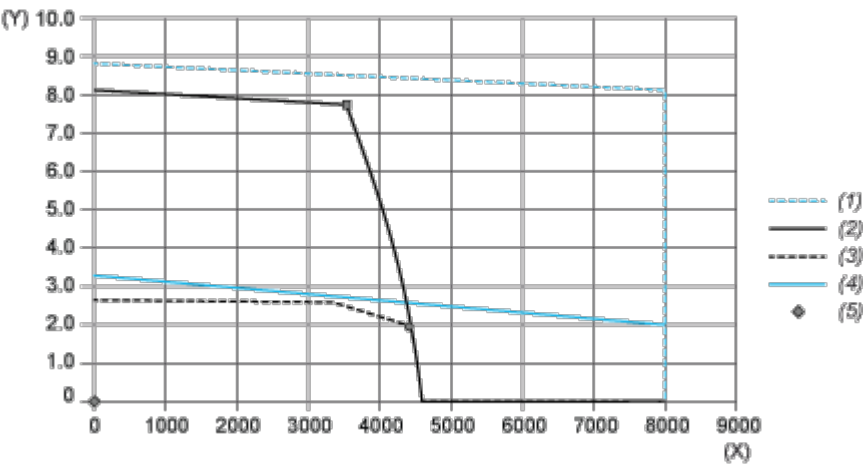
(4) Motor cont

(5) Operating point

		Power	At Speed	With Torque
max. Peak Power	■	2390 W	2960 rpm	7.71 N.m
max Cont. Power (Drive)	●	895 W	3760 rpm	2.27 N.m

Performance Curves

Torque/Speed Curves with 480 V Three Phases Supply Voltage



(X) Speed (rpm)

(Y) Torque (N.m)

(1) Motor peak

(2) Drive peak

(3) Drive cont

(4) Motor cont

(5) Operating point

		Power	At Speed	With Torque
max. Peak Power	■	2915 W	3600 rpm	7.73 N.m
max Cont. Power (Drive)	●	945 W	4560 rpm	1.98 N.m